

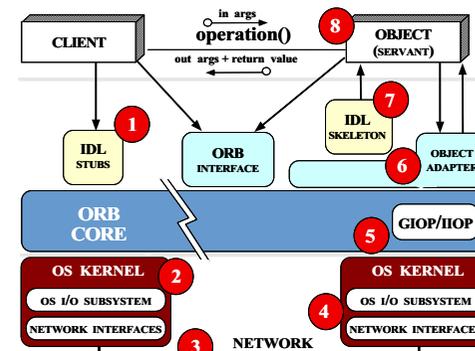
Resource Scheduling for Real-time ORBs

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Research on Resource Scheduling in Real-Time ORBs

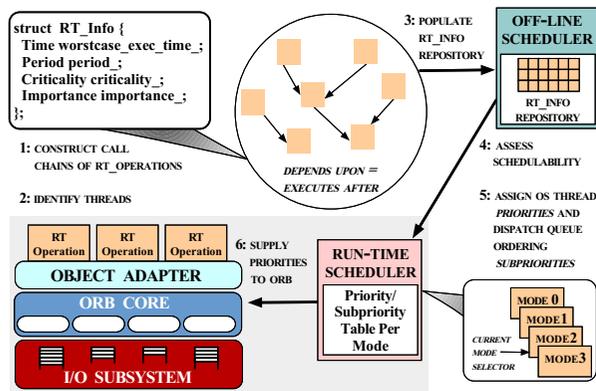


- 1) CLIENT MARSHALING
- 2) CLIENT PROTOCOL QUEUEING
- 3) NETWORK DELAY
- 4) SERVER PROTOCOL QUEUEING
- 5) THREAD DISPATCHING
- 6) REQUEST DISPATCHING
- 7) SERVER DEMARSHALING
- 8) METHOD EXECUTION

What makes an ORB real-time?

- QoS specification
 - * current focus: CPU resource requirements
 - * future focus: communication channels, memory, etc.
- Resource scheduling
 - * initial focus: static and dynamic, single-CPU
 - * current focus: dynamic, distributed

TAO's CPU Scheduling Service

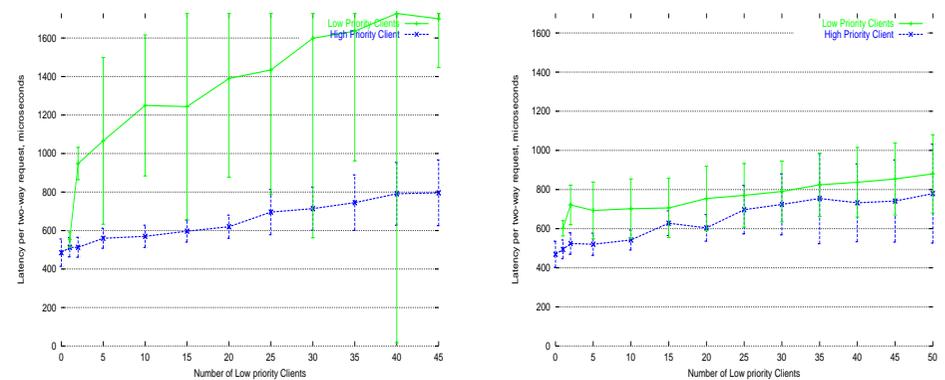


Solution Approach

- Integrate RT dispatcher into ORB
- Support multiple request scheduling strategies
 - e.g., MUF, which subsumes RMS, MLF, and EDF

www.cs.wustl.edu/~schmidt/TAO.ps.gz

TAO Performance on LynxOS 3.0.0



Server and Client on Same CPU

Server and Client on Different CPUs

Future Work

- Investigate performance on other real-time operation systems, notably VxWorks 5.3.1.
- Investigate performance on general purpose operation systems with real-time support, including Solaris 2.6, NT 4.0, and Linux 2.0.x w/KURT.
- Measure TAO overhead.
- Evaluate performance tradeoffs of dynamic scheduling.